AHE58-55 Instruction Manual

Safety Instruction

- Please read this manual carefully, also with related manual for the machinery before use the controller.
- For installing and operating the controller properly and safely, qualified personnel are required.
- Please try to stay away from arc welding equipment, in order to avoid electromagnetic interference and malfunction of the controller.
- Keep in room bellow 45° and above 0°
- · Do not humidity below 30% or above 95% or dew and mist of places.
- Install the control box and other components, turn off the power and unplug the power cord.
- To prevent interference or leakage accidents, please do the ground work, the power cord ground wire must be securely connected to an effective way to earth..
- · All parts for the repair, provided by the Company or approved before use.
- performing any maintenance action, you must turn off the power and unplug the power cord. There are dangerous high voltage control box, you must turn the power off after one minute before opening the control box.
- This manual marked with the symbol of the Department of Safety Precautions must be aware of and strictly adhered to, so as not to cause unnecessary damage.

1 Installation Instructions

1.1 Product specifications

Product Type: AHE58-55; maximum motor speed: 5000 r / min; Supply Voltage: AC 220 \pm 44 V; Power frequency: 50Hz/60Hz; Maximum output power: 550W; maximum motor torque: 3Nm.

1.2 Pedal installation

First, With self-tapping screws fastening the pedals①under the proper position of the platen ②.(direct drive servo motor ③and control box④has been fixed on the sewing machine head⑤). Then the two ends of the pedal connecting rod⑥ are connected with the pedals① and the bottom pedal⑦.

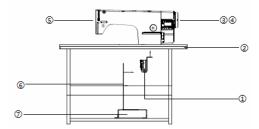


Fig.1-1 Direct drive machine controller installation diagram

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The footboard trys to ensure that the installation position is vertical rod pedals, the operator pedal is more comfortable and flexible.

1.3 Interface plug connections

The pedals and the machine head of the connector plug are mounted to the corresponding position in the controller back of socket, the name of each socket shown in Figure 1-2. Once connected, please check if the plug is inserted firmly.

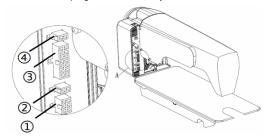


Fig.1-2 Controller Interface diagram

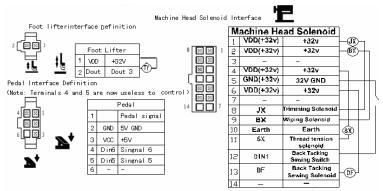


Fig.1-3 Controller Interface Definition

1: If the plug does not go in, check the plug and socket matches, needle insertion direction or the direction is correct! Light socket and presser foot lifter solenoid interfaces are 1 * 2 interface, head lights black connector interface, please note that distinction.

1.4 Wiring and Grounding

Must prepare the system grounding project, please be a qualified electrical engineer construction. Product is powered and ready for use, you must ensure that the power outlet the AC input is securely grounded. System grounding wire is yellow and green lines, make sure the ground wire is connected to the grid and reliable security protection on the ground to ensure the safe use, and prevent abnormal situation.

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All power lines, signal lines, ground lines, wiring not to be pressed into other objects or excessive distortion, to ensure safe use!

2 Operation Panel Instruction

2.1 Operation Panel Display Instruction

2.1.1 The operation panel composition

Operation Panel is divided with two areas (See Fig2-1): LCD display areas and key words area.

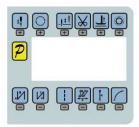


Fig.2-1 Operation Panel

2.1.2 The LCD display

The LCD display areas are position in middle of the whole operation panel. It including pattern, sewing mode, start/end back tacking, and foot lifter, stop-needles and trimming, and slow start operation set. The operation system automatically power on that HMI will a self-test, then all icons will flash once in the LCD display areas and only display the current settings of the system, the other did not choose that the icon will not be lighted, see figure 2-2.

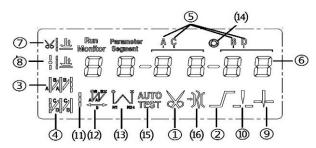


Fig.2-2 LCD Icon

Table 2-1 LCD Icon Display Description

| Index | Icon | Description | Index | Icon | Description |
|-------|------|---------------------|-------|------|---------------------------------------|
| 1 | * | Automatic trimming | 9 | 1 | Intermediate stops up stop position |
| 2 | 5 | Soft-start function | 10 | | Intermediate stops down stop position |
| 3 | 4 4 | start back tacking | 11 | | Free sewing |

| 4 | | End back tacking | 12 | W. | W seam |
|---|--------------|--|----|--------------|------------------|
| 5 | A C B D | Sewing segments index | 13 | | Multi-seam |
| 6 | 8 8-8 8-8 8 | Numeric character display (pin number / parameter) | 14 | | Trigger function |
| 7 | * <u> </u> 1 | Footlifter after trimming | 15 | AUTO TEST | Automatic test |
| 8 | | Middle stop footlifter | 16 |)((| Clamp function |

2.2 The operation panel keys of description

A description of each key operation panel shown in Table 2-2.

Table 2-2 : Key Functions instruction

| No | Appearance | Description |
|----|--------------------------|--|
| 1 | $\overline{\mathcal{P}}$ | Function key: Major operation to determine and confirm working, and work with other key to set |
| 1 | | a higher level of the parameter. |
| | | start back tacking key: Every effective press the key once; round with single start back tacking, |
| 2 | | double start back tacking, four start back tacking and close start back tacking. The current status |
| |) | is displayed on the left of LCD. Detailed see "3.1.2 before and after sewing settings instruction. |
| | | end back tacking key: Every effective press the key once; round with single end back tacking, |
| 3 | | double end back tacking, four end back tacking and close end back tacking. The current status is |
| | | displayed on the left of LCD. Detailed see "3.1.2 before and after sewing settings instruction. |
| 4 | | Free sewing mode key: Every effective pushed the key once; the system selects free sewing |
| 4 | | mode. The free sewing status is displayed below LCD. Detailed see "3.1.1 model sets of sewing." |
| 5 | CAPY | W sewing mode key: Every effective pushed the key once; the system selects W sewing mode. |
| J | | The W sewing status is displayed below LCD screen. Detailed see "3.1.1 model sets of sewing." |
| | ŀ | Multi-segment sewing mode key: Every effective pushed the key once; the system selects |
| 6 | | multi-segment sewing mode, pressed ${f P}$ key into the number of the needled setting. The |
| | | multi-segment sewing status is displayed below LCD. Detailed see "3.1.1 model sets of sewing." |
| 7 | | Soft start key: Select soft start function. It will show soft start status on top of LCD screen. |
| | | Stop position key: Select up/down stop position. The up/down stop position is displayed on top |
| 8 | 1:1 | of LCD screen. Detailed see "3.1.7 stop position set. [Note: automatic trimming back, the system |
| | + | is always on the up of needle position.] |
| 9 | + | Cycle key: Switch parameter position when change parameter; |

| No | Appearance | Description |
|----|--------------------------|---|
| 10 | + | Stitch compensation key: Start stitch compensation if press, stop stitch compensation if loose. |
| 11 | $\langle \times \rangle$ | Trimming key: Select/Cancel automatic trimming. The trimming status is displayed on top of LCD |
| 11 | + | screen. Detailed see "3.1.5 trimming set. |
| | J | Press foot lifting key: Every effective pushed the key once; round with trimming after press foot |
| 12 | | lifting, sewing end press foot lifting and manual press foot lifting. The current status is displayed |
| | + | on top of LCD screen. Detailed see "3.1.4 press foot lifting set. |
| | | One-Shot-Sewing key: Select/Cancel one-Shot-Sewing, it is effective only into multi-segment |
| 13 | + | sewing mode, when chose one-shot sewing, one-shot foot pedal can complete one needle of |
| 13 | | multi-segment sewing; The one-shot-sewing status is displayed on top of LCD screen. Detailed |
| | | see "3.1.6 trigger set. |

3 System Parameter Setting Description

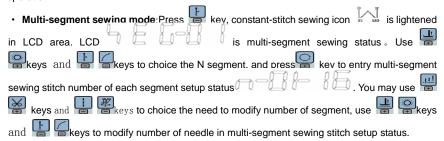
3.1 Operator Mode

In this mode, various sewing modes are available after technical parameters settings. As the default setting, the system enters this mode when it starts. Under this mode, such basic functions as normal sewing work and modes change can be realized but no change inside parameters and setting.

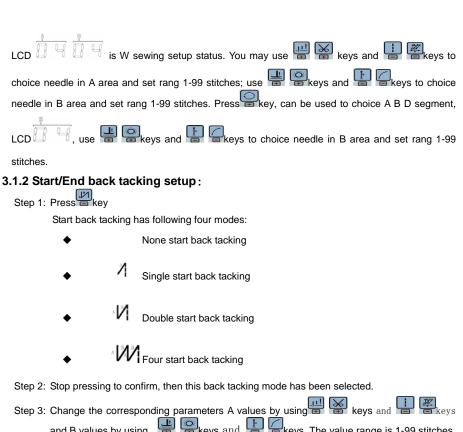
<u>^</u>: During working, if long time without press button, HMI will change to idle status automatically, and will cancel the operation before.

3.1.1 Sewing Mode Setup

• Free sewing mode:Press key, free sewing mode icon is lightened in LCD area. LCD indicates free sewing mode has been selected; it is ready just step the pedal for operation.



• W sewing mode: Press exey, constant-stitch sewing icon is lightened in LCD area. 第5 页 共16 页



and B values by using keys and keys. The value range is 1-99 stitches. It set pin number to be completed before star back tacking.

Note: End back tacking setting method is similar with start back tacking setting method basically, except the key.

3.1.3 Soft start setup:

Press key, entry into soft start status. If choice soft starts, the icon is lightened in LCD areas. Press this key again to exit soft start status, the icon will off.

3.1.4 Press foot lifting key:

Press key, entry into foot lifting status, total four different status, no automatic foot lifting. automatic foot lifting after trimming $(\sqrt[4]{\underline{u}})$, automatic foot lifting if stop during sewing $(\sqrt[4]{\underline{u}})$ automatic foot lifting if trimming and stop during sewing. Use key to choice foot lifting setup status and stop press key to confirm. Foot lifting had compiled.

3.1.5 Trimming key

If press key entry into press trimming status, select/non-select trimming. Press key

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repeat, the icon is lightened/ disappeared in LCD area. Whether it choice trimming that the icon is lightened or disappeared.

3.1.6 One-Shot-Sewing key

Use key: select/non-select one-shot-sewing statues. The icon will light if select one-shot-sewing in LCD areas, press will disappear.

3.1.7 Stop position key

Use key: select up/down stop position. Press key repeat, between up ____/down ____ stop position to switch. Choose need to stop position and stop press key to confirm. Stop position had compiled.

3.1.8 Stitch compensation key

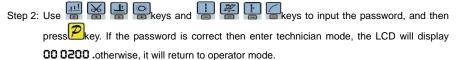
Use key: press this key to start stitch compensation. Compensation half needle or a half needle due to the press time. If you keep press that compensation needle always until release button.

3.2 Technician Mode

Technician mode is used for sewing speed and pedal speed control such as the use of performance adjustments.

3.2.1 How to enter the technician mode

Step 1: Under operator mode, press key and key, the LCD will display Pd 0000, and then set the password 0000 to enter technician mode.



Step 3: Change technician parameters by keys and keys. The parameters are shown in table 2.



Step 5: Under technician mode, press key, the panel will return to operator mode.

3.2.2 Technician mode parameter:

Table3-1:Technician mode parameter

| Mode | Parameter | Default | Rang | Comment |
|-------|-----------|---------|-----------|-----------------------------------|
| | 00 | 200 | 100 ~800 | Minimum sewing speed |
| | D I | 3500 | 200 ~5000 | Maximum sewing speed |
| | 02 | 3000 | 200 ~5000 | Maximum constant sewing speed |
| | 03 | 3000 | 200 ~5000 | Maximum manual back tacking speed |
| speed | 04 | 200 | 100 ~800 | Stitch compensation speed |
| 5,777 | 05 | 250 | 100 ~500 | Trimming speed |
| | 06 | 0 | 0 / 1 | Soft start Mode setup: |

| Mode | Parameter | Default | Rang | Comment |
|-----------------|-----------|---------|------------|---|
| | | | | 0: Soft start only after trimming |
| | | | | 1: Soft start after both trimming and stop |
| | 07 | 2 | ~ <u>9</u> | Soft start stitch number |
| | 08 | 200 | 100 ~800 | Soft start speed |
| | | | | System accelerate sensitivity (Direct drive transmission |
| | 09 | 20 | l ~20 | can be set up to a large value ; belt transmission don't set |
| | 0.1 | | | large value or too much noise and vibration. This parameter |
| | | | | do not affect the electrical) |
| | | | | System decelerate sensitivity (Direct drive transmission |
| | OR | 20 | l ~20 | can be set up to a large value ; belt transmission don't set |
| | | | | large value or too much noise and vibration. This parameter |
| | | | | do not affect the electrical) |
| | 10 | 1800 | 200 ~2200 | Start back tacking speed |
| | 11 | 1800 | 200 ~2200 | End back tacking speed |
| | 12 | 1800 | 200 ~2200 | Continuous back tacking speed |
| Back tacking | 13 | 24 | 0~70 | Start back tacking stitch compensation 1 |
| setup | 14 | 20 | 0~70 | Start back tacking stitch compensation 2 |
| | 15 | 24 | 0~10 | End back tracking stitch compensation 1 |
| | 16 | 20 | 0~70 | End back tracking stitch compensation 2 |
| | 30 | 0 | 0/1/2/3 | Pedal Curve mode setup: 0: Auto Calculated liner Curve (According to the highest speed automatic computation) speed Pedal forward angle |
| Pedal | 30 | 0 | 0/1/2/3 | Twosegment liner Curve.(You shall be free to set slow start after fast or fast start after slow,the parameters "31"and"32"cooperate with use) Speed Pedal forward angle |

| N/ 1 | D . | | , n | |
|------|-----------|---------|--------------|---|
| Mode | Parameter | Default | Rang | Comment |
| | | | | 2: Arithmetic Curve (the parameters [33] cooperate with use) Speed Speed Pedal forward angle 3: S curve (the operate control is very well, slow start after fast) Speed Pedal forward angle |
| | 31 | 3000 | 200 ~4000 | Two segment controls the speed slope: mid turning point speed RPM (two segment of turning point speed), the parameter[30] set to 1 effective. Speed Mid turning point speed Pedal forward angle |
| | 32 | 800 | 0 ~ 102Y | Two segment controls the speed slope: mid turning point of pedal Simulated value, the parameter[30] set to 1 effective, the value is between[38]and[39]. Speed mid turning point of pedal Simulated Pedal forward angle |
| | 33 | 2 | l <i>1</i> 2 | Arithmetic Curve supplementary parameter: the parameter[30] set to 2 effective. 1: Square (the low speed control is very well, slow start after fast); Speed Pedal forward angle |

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| Mode | Parameter | Default | Rang | Comment |
|-----------------|-----------|---------|----------|---|
| | | | | 2: Square root (Responding speed is fast, fast start after slow); |
| | | | | Speed Pedal forward angle |
| | 34 | 90 | 0 ~ 1024 | Pedal trimming position set, See 5-1. (the value is not higher than the parameter [35]) |
| | 35 | 300 | 0~1024 | Press foot lifting, See 5-1. (the value is between[34]and[36].) |
| | 36 | 4 19 | 0 ~ 1024 | Pedal back mid position, see 5-1. (the value is between[35]and[37].) |
| | 37 | 5 10 | 0 ~ 1024 | Pedal step upon running position, see 5-1. (the value is between[36]and[38]) |
| | 38 | 578 | 0 ~ 1024 | Pedal low speed running position (upper) ,see5-1 (the value is between[37]and[39]) |
| | 39 | 962 | 0 ~ 1024 | Pedal simulation the largest of value, see 5-1 (the value is not lower than the parameter [38]) |
| | 38 | 100 | 0 ~800 | Pedal press foot lifting confirm time |
| custom setup | 40 | I | 0/1 | Run to up needle position after Power on: 0: no action 1: action |
| | 41 | I | 0/ | Automatically reinforcing functions chose : (the machine head is not automatically reinforcing functions, the best way is prohibit) 0: prohibit 1: allow |
| | 42 | 0 | 0/1 | Back to sewing by hand when the function mode selection: 0: Juki mode. In sewing or in the end of the action 1: Brother mode. It acts only in sewing. |

| Mode | Parameter | Default | Rang | Comment |
|---------------|-----------|---------|-------------|--|
| | 43 | 0 | 0/1/2/ 3 | Special Running Mode setup: 0: operator select 1: simple sewing mode 2: calculate initial angle of motor (do not uninstall strap) 3: calculate motor/machine head run rate mode (synchronizer, do not uninstall strap) Torque boost up at low speed: |
| | 44 | 0 | 0-31 | 0: no action 1~31: 31 levels Torque boost up |
| | 45 | I | 0/ | Stop pin mode: 0: Constant speed tackle mode (in the belt transmission, Parking is not precision) 1: back pull mode (PMX) |
| | 46 | 100 | 0 ~800 | Command button to fill half-needle time |
| | 47 | 150 | 0 ~800 | Command button to fill a needle time |
| Count Mode | 50 | - | I~ I00 | Stitch counting proportion set up |
| Wode | 51 | - 1 | 1~9999 | Stitch counting value set up |
| | 52 | 0 | 0-4 | Stitch counting mode selection: 0: no counting 1: Counting up according to stitch number, after reaching set value then restart. 2: Counting down according to stitch number, after reaching set value then restart. 3: Counting up according to stitch number, after reaching set value, then motor should stop automatically, recounting should be restart by S4 [152.INI] = CRS or the button A on operation panel. 4: Counting down according to stitch number, after reaching set value, motor should stop automatically, recounting should be restart by S4 [152.INI] = CRS or the button A on operation panel. |
| | 53 | - | 1~ 100 | Trimming counting proportion set up |
| | 54 | 1 | 1~9999 | Trimming counting value set up |

| Mode | Parameter | Default | Rang | Comment |
|----------|-------------|---------|---------------|--|
| | 55 | 0 | D-4 | Trimming counting mode selection: 0: no counting 1: Counting up according to stitch number, after reaching set value then restart. 2: Counting down according to stitch number, after reaching set value then restart. 3: Counting up according to stitch number, after reaching set value, then motor should stop automatically, recounting should be restart by S4 [152.INI] = CRS or the button A on operation panel. 4: Counting down according to stitch number, after reaching set value, motor should stop automatically, recounting should be restart by S4 [152.INI] = CRS or the button A on operation panel. |
| Operatio | 61 | 0 | 0/1/2 | Translating Parameter 0: no action 1: Download parameters(the panel will parameter from panel to controller) 2: Upload parameters (the panel will parameter from controller to panel) |
| n | 62 | 0 | I, ≥, XXXX | Restore storage parameter(Only restore parameters to operators, and vendors and maintenance) Belt flat 1000/ Direct drive flat 2000 |
| | 63 | 0 | 1, 2 | Backup current parameter as user parameter for restore (restore) |
| | Note: Above | such "6 | Sx "parameter | to operate is not saved. |

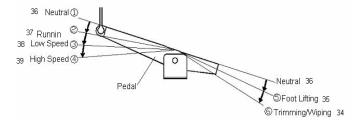


Fig.3-1 Pedal action parameter the position of the diagram

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3.3 Administrator mode

Administrator mode is used for functions such as sewing machine head solenoid adjustment.

3.3.1 How to entre administrator mode

Step 1: Under operator mode, presspand keys to enter administrator mode in LCD Pd 0000, and then set the password 0000 to enter administrator mode.

Step 2: The password is entered using the large with the password is correct then enter administrator mode, the LCD will display **QQ QQQQ**, or return to the operator mode.

Step 3: Change administrator parameters index by t keys and keys under administrator mode. The details of administrator parameters are shown in table3.

Step 4: Parameters values can be changed by

Step 5: Under administrator mode, press Rey, the panel will return to operator mode.

3. 3. 2 Administrator parameter table

Table 3-2: Administrator mode parameter:

| Mode | Parameter | Default | Rang | Comment |
|------------------------|-----------|---------|---------------|---|
| | 02 | ı | 0/1/2 /3 | Mode selection for trimming sequence. 0: According to the parameters [03] set angles is trimming, until up position delayed [06] time off. |
| Trimming mode | 03 | 10 | 5-359 | 1: According to the parameters [03] set angles is trimming, until [04] set angles off. 2: According to the parameters [03] set angles is trimming, it delayed [06] off. 3: Down position signal delayed the parameter [05] set angles is trimming, it delayed [06] off. |
| | 04 | 120 | 10 -359 | The start angles of trimming (relative down position of angle) |
| | 05 | 10 | I -999 | The end angles of trimming (relative down position of angle, Need to greater than the system of parameters [03]) |
| | 06 | 60 | 1-999 | Trimming start delay time T1 (ms) |
| Tension | 10 | 0 | 0/1/2 /3/4 | Trimming end delay time T2 (ms) |
| release 、 Wiper and | | 25 | 5 -359 | The start angles of tension release(relative down position of angle) |

| Mode | Parameter | Default | Rang | Comment |
|-----------------|-----------|---------|----------|---|
| Clamp mode | 12 | 350 | 10 -359 | The end angles of tension release (relative down position of angle, Need to greater than the system of parameters [11]) |
| | 13 | - 1 | I - 999 | Tension release solenoid start delay timeT1 (ms) |
| | 14 | ID | l - 999 | Tension release solenoid up position delay time T2 (ms) |
| | 15 | I | 0/1 | selection for Wiper function 0: off 1: on |
| | 16 | 10 | l - 999 | Clamp /Wiper delay time ms |
| | ١٦ | 70 | l - 9999 | Clamp /Wiper holding time ms |
| | 18 | 50 | I - 999 | Clamp /Wiper revert time ms |
| | 19 | 0 | 0/1 | Thread Clamp function: 0: off 1: on |
| | IR | סר | 0 - 359 | Clamp start angle |
| | ТЬ | 140 | 0 - 359 | Clamp end angle |
| | 3 | 0 | 0/1 | The automatic test mode selection : 0: order stitches 1: order time |
| Stop mode | 32 | 300 | O ~ 1000 | The safety SW alarm confirm time ms(the same way does not distinguish between direct-drive safety SW and flat lock trim of protection SW) |
| | 33 | 50 | 0 ~ 1000 | The safety SW restore confirm time ms |
| | 34 | 0 | 0/1 | Motor rotation direction setup: 1: Forward 0: Reverse |
| Machine head | 40 | 1000 | 0 - 9999 | motor/machine head run rate: 0.001 (if automatic calculation of motor/machine head run rate has done, the Parameter value in control box maybe different with that in HMI) |
| paramete | 42 | 0 | 0 - 359 | Up needle position adjusted angle (compare to up position sensor position excursion) |
| | 43 | 175 | 0 - 359 | Down needle position mechanical angle |
| | 44 | 200 | 0 - 800 | Press down delay time(ms) |

3.4 Monitor mode

3.4.1 How to enter monitor mode

During HMI idle, Press key, then press key, entry monitor mode. Use keys and keys to switch to watch the parameters. About the monitor parameter, please refer the sheet 4, HMI will back to idle if no wheel or no press the key in regulates time.

3.4.2 Monitor mode parameter table

Table 3-3 monitor mode parameter

| Name | Parameter | unit | comment |
|-------------------|-----------|--------|------------------------------------|
| Monitor status | 10 | | Counter stitches |
| | 11 | | Counter trimming |
| | 20 | V | DC Bus Voltage |
| | 2 | RPM | Motor speed |
| | 22 | 0. 01A | One phase current |
| | 23 | degree | Initial angle |
| | 24 | degree | Mechanical angle |
| | 25 | | Sampling value of pedal voltage |
| | 26 | 0.001 | motor/machine head run ratio |
| | 27 | hour | Motor total run time |
| | 38 | | Sampling value of potentiometer at |
| | | | machine head |

3.5 Wrong warning mode

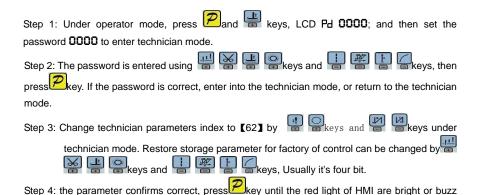
3.6 Safety switch warning mode

with the switch input, does not distinguish between safety switch, scissors protection switch)

4 Parameter reset to factory settings

4.1 Restore storage parameter for factory of control

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4.2 Adjust the up needle position

parameter.

Step 1: Press and keys, enter monitor mode to the NO. 24th monitoring parameters. As shown in Figure 4-2

produces a long loud, release key, HMI and the whole system restore storage

- Step 2: Turn the handwheel so that the wiper to the position of the up needle position, LCD will show a mechanical angle of deviation. As shown in Figure 4-2 Legend.
- Step 3: Press the and keys, LCD display 240000 (previous step mechanical deflection angle zero) to prove that the needle position set. As shown in Figure 4-2 Legend:







Fig 4-2

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