Automatic sewing machine Servo controller instructions

Preface



Please read this manual carefully, also with related manual for the machinery before use the controller. For installing and operating the controller properly and safely, qualified personnel are required.

This product is designed for specified sewing machines and must not be used for other purposes.

If you have any problem or any comment, please feel free to contact us.

Safety Instruction

- (1) All the instruction marked with sign All must be absolutely observed or executed; otherwise, personal injuries or risk to the machine might occur.
- (2) This product should be installed and operated by persons with appropriate training only.
- (3) Before connecting power supply cords to power sources, it's necessary to make sure that the power voltage is in the range indicated on the product name plate.
- (4) Make sure to move your feet away from the pedals while power on.
- (5) **Turn off the power and remove plug prior to the following** operations:
 - Connecting or disconnecting any connectors on the control box;
 - Repairing or doing any mechanical adjustment;
 - Threading needle or raising the machine arm;
 - Machine is out of work.
- (6) Make sure to fasten all the fasteners firmly in the control boxes prior to the operation of the system.
- (7) Allow an interval of at least 30 seconds before repapering the system after power off.

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- (8) Repairs and maintenance work may be carried out by special trained electronic technicians.
- (9) All the replacement parts for repairing must be provided or approved by the manufacturer.
- (10) The controller must be firmly connected to a properly grounded outlet.
- (11) Ground wire installation (special attention).

CAUTION: Be sure to connect the controller to a properly grounded outlet. If the grounding connection is not secured, you may run a high risk of receiving a serious electric shock, and the controller may operate abnormally.

1. Basic parameters

Controller Type	AKD58-50
Max. Sewing Speed (r/min)	7000
Voltage Range	AC 220±20% V 50/60HZ
Output Power	550W
Max. Torque	3.5Nm
Environment	0° C \sim 40 $^{\circ}$ C

2. Secure wiring and grounding

The system is powered and ready for use, you must ensure that the AC input is securely grounded (Figure 2-1). System grounding wire is yellow and green lines, make sure the ground wire securely connected to the machine head (such as connecting to the head of the screw), in order to ensure the safe use, and prevent abnormal situation.



Fig.2 -1 Controller power wiring diagram

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Ensure all power cord, signal wire and grounding wire not be pressed by other matter or over-twisted ,and not be too close to belt and belt wheel, keep 3cm-distance for safety.

A 1Φ/220V power from a 3Φ/380V Power source Connection (See Fig.2-2):



If the system have no Neutral point, then this servo motor is not suitable for this connection.



Fig. 2-2 Three-phase power wiring diagram

3. Definition of controller interface

6 1

9 4

10 5

7 2

8 3

Connections between control box and other accessories are illustrated in Fig.3-1. Plug these connectors into the corresponding sockets in control box.





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	<u>+ L</u>							
	Foot Lifter							
1	VDD(+32v)	+32v						
2	TY	Foot Lifter						
	E							
M	achine He	ead Solenoid	k					
1	VDD(+32v)	+32v		8 1				
5	VDD(+32v)	+32v						
3								
4	GND(+32v)	32V GND		9 2				
5	GND(+32v)	32V GND						
6	VDD(+32v)	+32v		10 3				
7	VDD(+32v)	+32v						
8	JX	Trimming Soleno	d	11 4				
9	XTXF	Thread suction output						
10	Earth	Earth		12 5				
11	DIN	Input 0						
12	DIN1	Input 1		13 6				
13	BLXF	Fabrics suction output		14 7				
14	TYJ	Foot Lifter outpu	t					



* The drive ability of the LED jack:

Which the rated current is100mA and the rated voltage is 5V, the output current is adjustable.

Recommendatory LED diode parameter as follows:

VF: Min. = 3.0V, Max. = 3.6V (test condition IF = 20mA);

Peak Forward Current: Max. = 80mA;

Continuous Forward Current : Max. = 35mA

Caution: Please check if all connectors match or not, pins are found right definition or not.

4. Operation Panel Instruction

4.1 Appearance and key

The front operation panel (See Fig4-1) is provided with a status indicator divided, LCD display area and keys operation area.

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Fig.4-1 Automatic bag sewing Chinese panel display

There are13 keys in the key operation area that used to set the over lock sewing machine kinds of operation control parameters. There are 4 display lights at the top of the Panel that used to display real-time it operating status. F-SENSOR lights and B-SENSOR lights indicate front edge sensor and back sensor to status, light is lit indicate cloth cover sensor, light is not lit indicates that the sensor is not blocked; RUN light is lit indicates the rotation of the motor running; SAFE light is lit indicates a safety switch open. Table 2 shows function of each key.

No	KEY	Description
1	Ρ	Main menu key: Return to the main interface, or work with other key.
2	Ø	Automatic mode selection keys: The sensor is open, pressed in succession followed by optional automatic or semi-automatic mode.
3	Ċ	Suck selection keys: When sewing is selected suction mode, continuous press are optional before suction, back suction, before and after suction and suck the closure of four modes.
4	F	Speed selection key: To set the maximum sewing speed.
5	*	Trimming selection key: When sewing is selected trimming mode, continuous press are optional front trimming, back trimming, front and back trimming, and trimming the closure of four modes.

Table 2: Following	form is	the instru	iction of	each	key:

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6	9	Edge mode selection key: When sewing is selected working mode of mop wheel, continuous press are optional before mop wheel, rear mop wheel, before and rear mop wheel ,and the mop wheel closure of four modes.
7	S	Save to determine key: To save the parameters set.
8		Up arrow keys: When setting parameters, increasing the value at the cursor.
9		Down arrow keys: When setting parameters, decreasing the value at the cursor.
10		Left arrow key: When setting parameters, move the cursor to the left; Front trimming length shortcuts.
11		Right arrow key: When setting parameters, move the cursor right; Back trimming length shortcuts.
12	<u></u>	Machine headlight key: To adjust machine headlight brightness, followed by optional 0-4 consecutive press.
13	Ø	Sensor selection key: To open or close the electric eye. Electric eye closure enters manual mode, the sensor does not work; to open electric eye sensor is working, and then enter the semi-automatic mode or automatic mode.

4.2 The main interface and function key setting

The control panel is correctly inserted corresponding interface electrical control box; confirm security turn on the power. Boot for about 2 seconds, the LCD will display the main interface, shown in Figure4-2. If it is not a normal display and a fault alarm, please refer to Chapter 3 false alarms table, deal with the corresponding failure or contact the manufacturer.



In Fig. 1-2 system main interface, press the Pkey, then displays the current settings for automatic sewing machine working status, shown in Fig.4-3.



Fig. 4-3 the current operating mode

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Wherein, the icon shows electric eye switch status, the icon shows the current trimming mode, the icon shows the current mop wheel mode, the icon shows the current suction mode. Press the key to return to the main interface. If you do not operate for about 10 seconds, the system will automatically return to the main interface mode.

In the main interface (show to fig.1-2), respectively press the function key (B,O,O,A,A,A), you can change corresponding to the operating mode. Press the $\fbox{A},\textcircled{A},\textcircled{A},\textcircled{A})$, you can set the maximum operating speed of the sewing machine. Pass A and E keys to move the cursor, A and E keys to change the number. After it is set, press the P key to exit and return to the main interface.

4.3 Work mode setting

Automatic sewing machine system according to need can work in manual mode, semi-automatic mode, automatic electric control mode and automatic foot control mode. Wherein the manual mode entirely by foot pedals to control the sewing machine operation, this time electric eye closed, detection and automatic trimming function is invalid; semi-automatic mode is defined by the sensors and pedal to control sewing machine operation, this time electric eye open, pedals and trimming are valid; Automatic power control mode is completely controlled by the electric eye sensor automatic sewing machine presser foot, start, and stop trimming cycle operation; automatic mode through the foot control electric eye sensor control automatic presser foot, by the foot pedal before starting sewing. During sewing foot pedal will be suspended after the sewing step before proceeding to continue automatic sewing processes. Automatic mode is entirely controlled by the electric eye open, pedals do not control the sewing machine, the timing of each function only by the electric eye automatic detection and control.

Sewing mode	Electric eye on or off	fully automatic mode selection
manual mode	off	invalid
semi-automatic	on	semi-automatic
automatic electric control	on	automatic electric control
automatic foot control	on	automatic foot control

Table 3: over lock sewing pattern corresponding relationship

Example: If the current to full manual mode, the actual status at this time electric eye

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switch is off, the main interface shown in Figure 4-4.



Fig. 4-4 manual system main interface

Press the 4-5.



Press the key again, electric eye switch immediately opens, displaying electric eye switch is turned on, as shown in Figure 4-6, then press the key to confirm automatic sewing mode, if the current mode is automatic sewing mode, shown in Figure 4-7; when the current sewing mode is semi-automatic mode, shown in Figure 4-8.



In the current electric eye switch remains open in the case, press the key, in automatic and semi-automatic mode switching. After it is set, press the key to exit.

4.4 The maximum speed setting

Press the F key, then the system will run set to the current maximum speed shown in Figure 4-9.



Fig. 4-9 system current maximum speed

Fig. 4-10 set system maximum speed

Then you can use the keys to move the cursor, keys to change the number, the maximum speed is displayed after the change shown in Figure 4-10. After setting, press the key to exit.

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4.5 Front and back trimmings length shortcuts of adjustment

In the main interface, the (I), key can be respectively front and back trimmings

length shortcuts adjustment, ▲, ▼key to change the numbers, which will be effective simultaneously. As shown in figure 4-11.



Fig. 4-11 Front and back trimmings length setup

5. Advanced Features

5.1 Conversion between the Chinese and English

In the main interface, press Pkey + Fkey to complete the switch in English, as shown in Figure 5-1 and 5-2, press Pkey +Fkey to switch back to the Chinese interface.



5.2 Technicians parameter settings

In the main interface under, press key + key, to enter the technician parameter setting's password interface, shown in Figure 5-3.



Technician's parameter password can press \blacktriangleleft and \blacktriangleright keys to move the cursor, press \blacktriangle and \checkmark keys to change the number, the initial password is $\square \square \square$. Enter the correct password; press the \bigcirc key to enter the machine repair parameter settings shown in Figure 5-4.

00 0003]
Auto Foot Mc	de

Fig. 5-4 the machine repair parameter settings

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Figure 2-4 shows the current system parameter list. The before two digits of the parameter number, the last four digits of the parameter value. Text below the parameter's instructions. You can press \blacksquare and \blacksquare keys to move the cursor, press \blacksquare and \blacksquare keys to change the number, select the number of different parameters and setting the corresponding parameter values. If you need to save and exit, press \bigcirc key, otherwise press \bigcirc key.

5.3 Restore factory settings

In the main interface, press P key+ key, enter the correct password, press skey to enter the technician parameters. Select the B^2 parameters and corresponding values to 2008, shown in Figure 5-5.



Fig.5-5 Parameter reset to factory

In Figure 5-5 interface, press [5] for two seconds until the screen show in Figure 5-6, wait for about 5 seconds, the buzzer rang long after the recovery is complete. (Hint: the recovery process should not turn off the power or unplug the panel!)



Fig.5-6 Parameter reset to factory

5.4 Automatic test mod

In the main interface press Pkey+Skey to enter the automatic test setup interface, you can press and keys to switch running time, stop time, test time, press and keys to change the corresponding figures. Running time, stop time in units of 0.1 seconds, the unit test time is 10 minutes.



Fig.5-7 the main interface

Fig.5-8 automatic test parameter setting interface

In Figure 5-8 interface, press P key+S key again, which enters the automatic testing process, shown in Figure 5-9, then light foot pedalling to start the automatic test.

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TESTING!!!

Fig.5-9 automatic test run interface

To exit test mode to run automatically, you can press Pkey+Skey, the motor stops running, the automatic end of the test and return to Figure 5-8 interface, press the Pkey again to return to the main interface.

5.5 Monitor Mode

In the main interface, press P key+ \aleph key to enter monitor mode, you can view the current system parameters, the specific content shown in Table 4.

	Parameter No.	Comment
	10	Counter stitches
		Counter trimming
	20	DC Bus Voltage
	51	Motor speed
	22	One phase current
Monitor	53	Initial angle
status	24	Mechanical angle
	25	Sampling value of pedal voltage
	26	Motor/machine head run ratio
	27	Motor total run time
	28	Sampling value of potentiometer at machine head
	29	DSP Software version number
	30-3F	History Error Code Recorder 8

Table 4: monitor mode parameter

6 Technician parameter setting

In the main interface, Pkey+ key to enter the technician parameters, Table 5 can view and modify the parameters, mainly the system speed, a variety of automatic feature set, pedal settings and parameters transfer functions.

Table 5: Technician mode parameter:

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	Parameter byte	Default	Rang	Comment
	пп	7	сп	Auto foot lifter setup: 0 off ; 1 Before foot lifter; 2 Back foot
	00		U-J	lifter; 3 Before and Back foot lifter
	01	0	0/ 1	Speed mode: 0 automatic; 1 pedal control speed
	02	٥	0/ 1	The needle stop position: 0 up needle position; 1 down needle position
	03	٥	0/ 1	Foot lifter setup when the needle stop in the middle position: 0 off; 1 automatic foot lifter
	04	-	0/ 1	Manaul stitch suck mode: 0 off; 1 on
crood	05	3000	2 0 0-4 200	Automatic sewing speed
speed	06	5000	400-6500	Maximum sewing speed
		_		Semi automatic continuous sewing: 0 automatic stop back
	υı	i	U/I	trimming ; 1 Tread the pedal for sewing
	08	2	0/1/2	Semi automatic constant speed: 0 Full constant speed; 1 The
				pedal control it when the two sensor is effectively at the same
				time; 2 Full pedal control
	09	200	100-800	Minimum speed
	DR	300	100-800	Treading needle speed (retain)
		20	0-50	Front sensor operation and effective number of stitches (front sensor sensor automatically go pin number, completed after the sensor still no sense if you stop pin)
Automatic function setup	11	20	1-50	Number of needle between the two sensors (front sensor signal disappeared, after the sensor is sensed to continue sewing needle;
	12	2	1-50	The before Trimming delay needle (FB = 11 signal start count needle)
	13	9	1-50	The back Trimming delay needle (FB = 0 0 signal start count needle)
	14		1-50	The before suction start needle (FB = [] signal start count needle)
	15	0	0-5000	The before suck delay time (ms)

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	Parameter byte	Default	Rang	Comment
	16		1-50	The back suction start needle (FB = 0 0 signal start count needle)
	П	300	100-5000	The back suck off delay time(ms)
	18	-	D- I	Suck mode: 0 when the motor is running long suction; 1 automatic mode suction
	19	200	100-5000	When it is running suction of delay time, long suction can be back stepped or manual trimming Close
	IR	3000	0-5000	Automatic mode is completed, parking, needle of number running speed
	16	10	10-5000	Start sewing delay time (Retain)
	IC	10	1-99	Stop delay pins (rear sensor signal disappeared after count sewing needle number, $FB = 00$ signal begins to count)
	Ы	10	0-99	Automatic mode is completed, parking, rear number of stitches
	ΙE	500	0-5000	Automatic mode is completed, parking, walking up the end of the solenoid valve A new opening time ms
	١F	500	0-5000	New solenoid valve A is closed,new solenoid valve B is open , open time ms
	20	10	I- 1000	The before sensor response time
	21	680	0- 1024	The before sensor sensitivity (According translucent fabric manually adjust the sensitivity of sensor)
	22	680	0- 1024	The back sensor sensitivity (According translucent fabric manually adjust the sensitivity of sensor)
Automatic	23	280	10-2000	The before foot lifter retention time (FB = 10singal begins to count)
function setup	24		1-2000	The back foot lifter start up delay time(back trimming stop ,it begins to count)
	25	3	1-600	Foot lifter protection time 100ms
	26	30	20-800	The before foot lifter stop of delay time(ms) (press down foot to start sewing the interval)

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	Parameter	Defeuilt	Dana	Comment
	byte	Default	Rang	Comment
				Automatic mode recognized work cycle:
				0: After trimming before halfway out of the cloth, not after
				trimming action, once again put the cloth will not be executed
				before the cut line, until after the cut line, be considered a work
	27	0	0/ I	cycle ends.
				1 : Regardless of whether the thread trimming after completion,
				as long as the cloth out, are recognized as a work cycle. Again
				into the fabric, which began a new working cycle and run
				before trimming
	28	0	0/1	It is running manual trimming: 0 off; 1 on
	29		0/1	Safety switch: 0 off; 1 on
	28	35	I- 1000	Trimming keep start time
	ا ر	רור	חבי	Acceleration sensitivity (direct drive head can be set to a
	כס	CU	1-2'U	larger value; belt drive can not be set too big, otherwise
	20	20	1-20	Deceleration sensitivity (The direct drive head can be set to a
				larger value; The belt drive can not be set too big, otherwise
				vibration, noise is big. The parameter does not affect the motor
				output)
	59	1000	200- 1200	The medium speed value (RPM)
pedal	32	50	25-200	The low speed value (RPM)
	25	250	20-600	Full manual mode foot lifter delay time ms
	BR	100	0 ~800	Pedal press foot lifting confirm time
	-1			Run to up needle position after Power on:
	36	i	U/ I	0: no action 1: action
				Special operating modes:
				0: Operator mode (common functions)
	7.5	_	- / - / - / -	1: Simple sewing mode (no needle stop up or down)
	ΞL	U	U/I/d/J	2: Measured motor initial angle (no need to remove the belt)
				3: Calculate the gear ratio mode (requires needle sensor, and
				can not take off the belt)

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	Parameter byte	Default	Rang	Comment
	38	0	0~31	Torque boost up at low speed : 0: no action 1~31: 31 levels Torque boost up
	ЗE	1	0 / 1	Stop pin mode : 0 : Constant speed tackle mode (in the belt transmission, Parking is not precision) 1 : back pull mode (PMX)
Operation	60			It is running time reset
	61	-	07172	 Translating Parameter 0: no action 1: Download parameters(the panel will parameter from panel to controller) 2: Upload parameters (the panel will parameter from controller to panel)
	62	-	-	Restore storage parameter(Only restore parameters to operators, and vendors and maintenance)
	63	٥	1/2	Backup current parameter as user parameter for restore (restore)

7Recovery processing and maintenance

Table 6: Error handling and maintenance

error code	meaning	solution
01	hardware overflow	Turn off the system power, restart after 30 seconds, if the controller still does not work, please replace it and inform the manufacturer.
02	software overflow	
03	system under-voltage	Disconnect the controller power and check if the input voltage is too low (lower than 176V). If yes, please restart the controller when the normal voltage is resumed. If the controller still does not work when the voltage is at normal level, please replace the controller and inform the manufacturer.
04	over-voltage when the machine is off	Disconnect the controller power and check if the input voltage is too high (higher than 264V). If yes, please restart the controller when the
05	over-voltage in operation	normal voltage is resumed. If the controller still does not work when the voltage is at normal level, please replace the controller and inform the manufacturer.
06	solenoid circuit failure	Turn off the system power, check if the solenoid is connected correctly and if it is loose or damaged. If yes, replace it in time. Restart the system upon making sure everything is in good order. If it still does not work, seek technical support.

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٢٥	electrical current checking circuit failure	Turn off the system power, restart after 30 seconds to see if it works well. If not, try several more times. If such failure happens frequently, seek technical support.
08	locked motor roller	Disconnect the controller power, check if the motor input plug is off, loose or damaged, or if there is something twined on the machine head. After checking and correction, if the system still does not work, please replace the controller and inform the manufacturer.
09	brake circuit failure	Turn off the system power, check if the white brake resistance plug on the power board is loose or dropped off, fasten it and restart the system. If it still does not work, please replace the controller and inform the manufacturer.
10	HMI communication failure	Check if the connecting line between control panel and controller is off, loose or broken, restore it and restart the system. If it still does not work, please replace the controller and inform the manufacturer.
11	machine head needle positioning failure	Check if the connection line between machine head synchronizer and controller is loose or not, restore it and restart the system. If it still does not work, please replace the controller and inform the manufacturer.
15	motor original angle checking failure	Please try 2 to 3 more times after power down, if it still does not work, please replace the controller and inform the manufacturer.
13	Motor HALL failure	Turn off the system power, check if the motor sensor plug is loose or dropped off, restore it and restart the system. If it still does not work, please replace the controller and inform the manufacturer.
14	DSP Read/Write EEPROM failure	Try another time after power down, if it still does not work, please replace the controller and inform the manufacturer.
15	Motor over-speed protection	Turn off the system power, turn on again in 30 seconds to see if it works. If not, try several more times, if such failure happens frequently, please change the controller and inform the manufacturer.
16	Motor reversion	Turn off the system power, restart the system after 30 seconds, if it still does not work, please replace the controller and inform the manufacturer.
Г	HMI51 Read/Write EEPROM failure	Turn off the system power, restart the system after 30 seconds, if it still does not work, please replace the controller and inform the manufacturer.
18	Motor overload	Turn off the system power, restart the system after 30 seconds, if it still does not work, please replace the controller and inform the manufacturer.
20	Lack of oil alarm	Add oil to the needle rod, and set the P22 parameter at 4000, resume the working time after the last oil adding; or you can press button P to close the alarm and continue to use.
51	Sensor error	Check with the sensor parameters and whether it is normal. If normal, please replace the sensor.

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